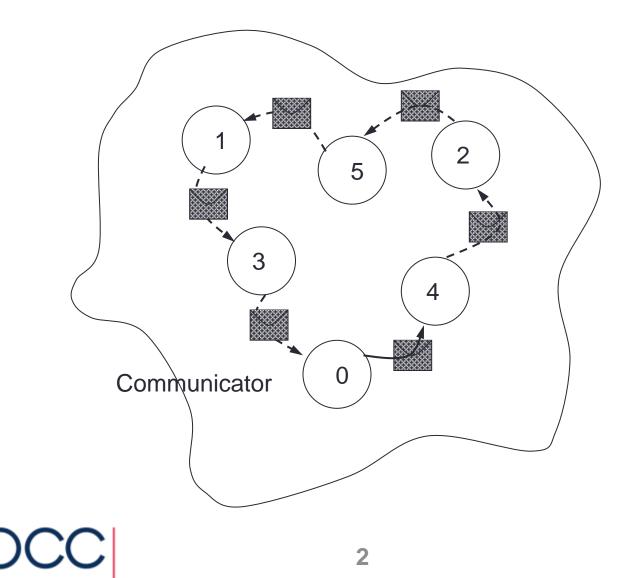
Non-Blocking Communications





Deadlock





Completion

- The *mode* of a communication determines when its constituent operations complete.
 - i.e. synchronous / asynchronous
- The *form* of an operation determines when the procedure implementing that operation will return
 - i.e. when control is returned to the user program





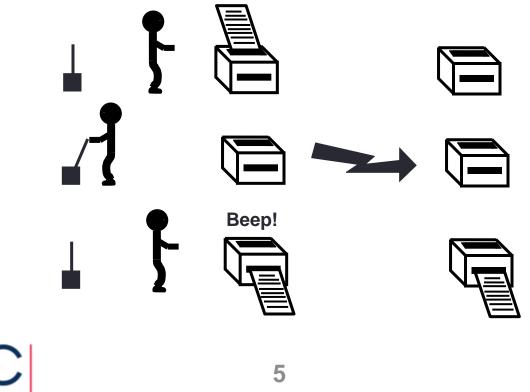
Blocking Operations

- Relate to when the operation has completed.
- Only return from the subroutine call when the operation has completed.
- These are the routines you used thus far
 - MPI_Ssend
 - MPI_Recv



Non-Blocking Operations

 Return straight away and allow the sub-program to continue to perform other work. At some later time the sub-program can *test* or *wait* for the completion of the non-blocking operation.





Non-Blocking Operations

- All non-blocking operations should have matching wait operations. Some systems cannot free resources until wait has been called.
- A non-blocking operation immediately followed by a matching wait is equivalent to a blocking operation.
- Non-blocking operations are not the same as sequential subroutine calls as the operation continues after the call has returned.





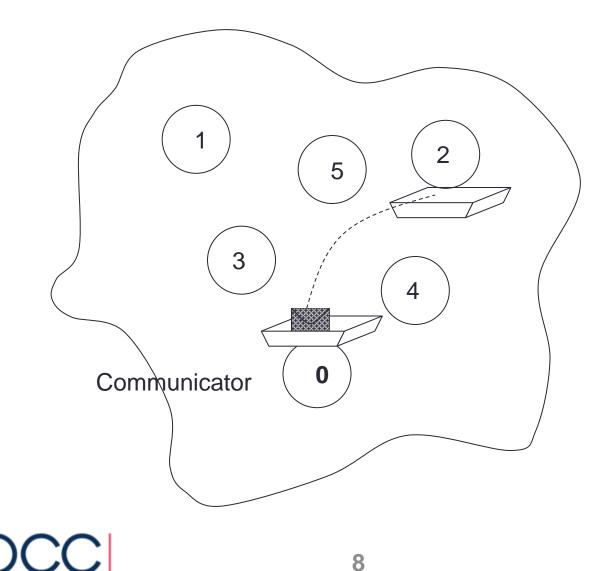
Non-Blocking Communications

- Separate communication into three phases:
- Initiate non-blocking communication.
- Do some work (perhaps involving other communications?)
- Wait for non-blocking communication to complete.



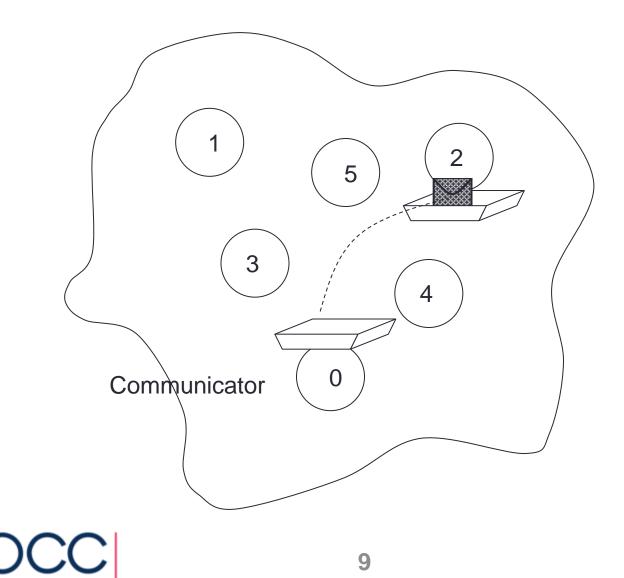


Non-Blocking Send





Non-Blocking Receive





Handles used for Non-blocking Comms

- datatype same as for blocking (MPI_Datatype or INTEGER).
- communicator same as for blocking (MPI_Comm or INTEGER).
- request MPI_Request or INTEGER.
- A request handle is allocated when a communication is initiated.





Non-blocking Synchronous Send

• Fortran:

MPI WAIT (request, status, ierror)





Non-blocking Receive

• Fortran:

MPI_WAIT(request, status, ierror)



Blocking and Non-Blocking

- Send and receive can be blocking or non-blocking.
- A blocking send can be used with a non-blocking receive, and vice-versa.
- Non-blocking sends can use any mode synchronous, buffered or standard
- Synchronous mode affects completion, not initiation.



Communication Modes

NON-BLOCKING OPERATION	MPI CALL
Standard send	MPI_ISEND
Synchronous send	MPI_ISSEND
Buffered send	MPI_IBSEND
Receive	MPI_IRECV



Completion

• Waiting versus Testing.

• C:

• Fortran:

MPI_WAIT(handle, status, ierror)

MPI_TEST(handle, flag, status, ierror)



Example (C)

```
MPI Request request;
MPI Status status;
if (rank == 0)
    MPI Issend(sendarray, 10, MPI INT, 1, tag,
               MPI COMM WORLD, &request);
    Do something else while Issend happens();
    // now wait for send to complete
    MPI Wait(&request, &status);
else if (rank == 1)
    MPI Irecv(recvarray, 10, MPI INT, 0, tag,
                MPI COMM WORLD, &request);
    Do something else while Irecv happens();
// now wait for receive to complete;
   MPI Wait(&request, &status);
```



Example (Fortran)

integer request
integer, dimension(MPI_STATUS_SIZE) :: status

```
if (rank == 0) then
```

```
CALL MPI_ISSEND(sendarray, 10, MPI_INTEGER, 1, tag,
MPI_COMM_WORLD, request, ierror)
CALL Do_something_else_while Issend_happens()
! now wait for send to complete
CALL MPI_Wait(request, status, ierror)
```

```
else if (rank == 1) then
```

```
CALL MPI_IRECV(recvarray, 10, MPI_INTEGER, 0, tag,
MPI_COMM_WORLD, request, ierror)
CALL Do_something_else_while Irecv_happens()
! now wait for receive to complete
CALL MPI Wait(request, status, ierror)
```

endif



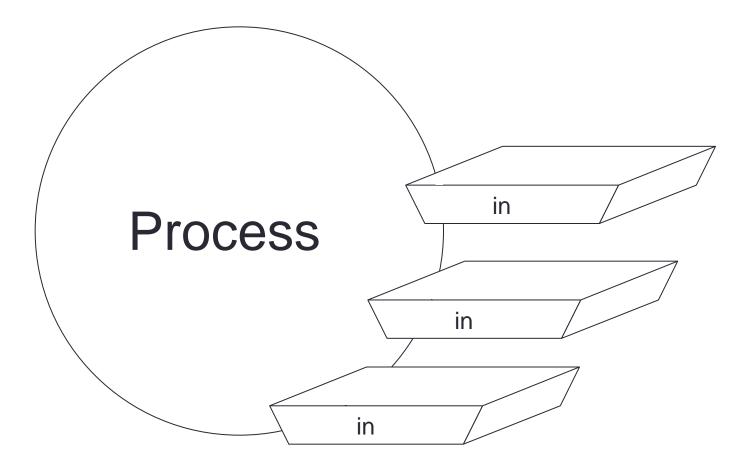
Multiple Communications

- Test or wait for completion of one message.
- Test or wait for completion of all messages.
- Test or wait for completion of as many messages as possible.





Testing Multiple Non-Blocking Comms





Combined Send and Receive

- Specify all send / receive arguments in one call
 - MPI implementation avoids deadlock
 - useful in simple pairwise communications patterns, but not as generally applicable as non-blocking





Rotating information around a ring

- See Exercise 4 on the sheet
- Arrange processes to communicate round a ring.
- Each process stores a copy of its rank in an integer variable.
- Each process communicates this value to its right neighbour, and receives a value from its left neighbour.
- Each process computes the sum of all the values received.
- Repeat for the number of processes involved and print out the sum stored at each process.



Possible solutions

- Non-blocking send to forward neighbour
 - blocking receive from backward neighbour
 - wait for forward send to complete
- Non-blocking receive from backward neighbour
 - blocking send to forward neighbour
 - wait for backward receive to complete
- Non-blocking send to forward neighbour
- Non-blocking receive from backward neighbour
 - wait for forward send to complete
 - wait for backward receive to complete



Notes

- Your neighbours do not change
 - send to left, receive from right, send to left, receive from right, ...
- You do not alter the data you receive
 - receive it
 - add it to you running total
 - pass the data unchanged along the ring
- You *must not access* send or receive buffers until communications are complete
 - cannot read from a receive buffer until after a wait on irecv
 - cannot overwrite a send buffer until after a wait on issend



